

JS series

JS/JSTH series

New Multi Purpose SCARA Robot

250/350/450/550

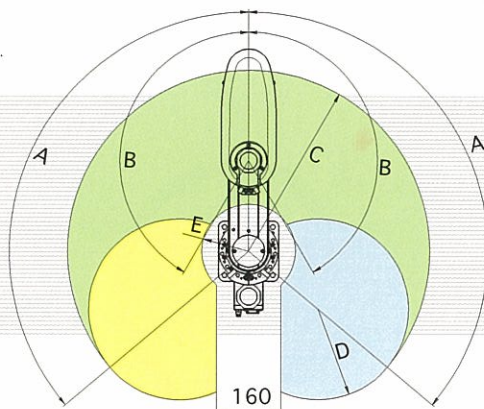
350TH/450TH/550TH

650TH/750TH/880TH/1000TH



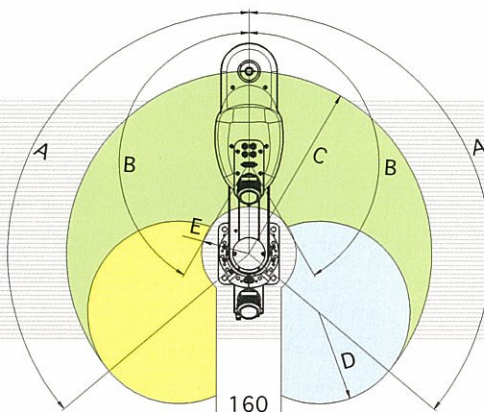
Operation Range

**JS 250
350
450
550**



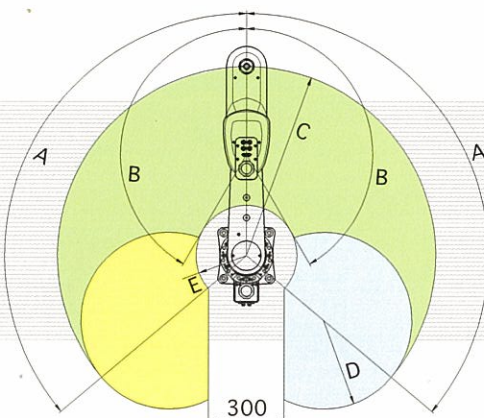
MODEL	A	B	C	D	E	Z stroke
JS250	130°	130°	R250	R150	R89	150
JS350 (CL)			R350		R132	
JS450 (CL)		150°	R450	R225	R116	
JS550 (CL)			R550		R172	

**JS 350TH
450TH
550TH**



MODEL	A	B	C	D	E	Z stroke
JS350TH	130°	150°	R350	R225	R132	200
JS450TH			R450		R116	
JS550TH			R550		R172	

**JS 650TH
750TH
880TH
1000TH**



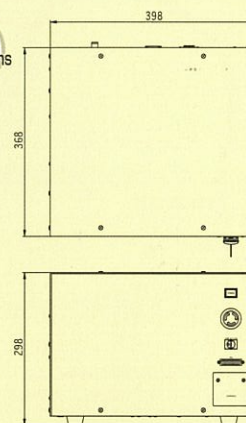
MODEL	A	B	C	D	E	Z stroke
JS650TH	130°	150°	R650	R350	R175	200
JS750TH			R750		R200	
JS880TH		160°	R880	R480	R172	
JS1000TH			R1000		R178	

Controller

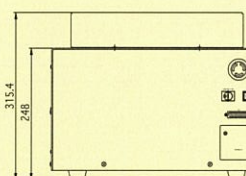
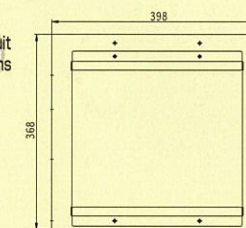


External Dimensions

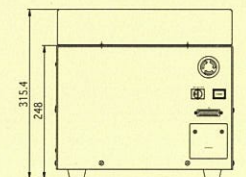
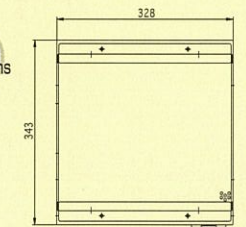
Full CE Specifications



Safety Circuit Specifications



Standard Specifications



JS series

JS 250



JS 350



JS 450



JS 550



JS series Specifications

Item	Model	JS250	JS350	JS450	JS550
Axis Type		4 (synchronous control)			
Arm Length	J1 Arm	100mm	125mm	225mm	325mm
	J2 Arm	150mm	225mm	225mm	225mm
	J1+J2	250mm	350mm	450mm	550mm
Operation Range	J1 Arm	±130°	±130°	±130°	±130°
	J2 Arm	±145°	±150°	±150°	±150°
	Z-Axis	150mm	150mm	150mm	150mm
	R-Axis	±360°	±360°	±360°	±360°
Maximum Portable Weight		4kg	6kg	6kg	6kg
Acceptable Moment of Inertia		0.1kg·m ²	0.1kg·m ²	0.1kg·m ²	0.1kg·m ²
Maximum Speed ^{*1}	J1 and J2 (combined)	4,200mm/sec	6,300mm/sec	5,600mm/sec	6,200mm/sec
	Z-Axis	1,400mm/sec	1,850mm/sec	1,850mm/sec	1,850mm/sec
	R-Axis	1,750°/sec	1,900°/sec	1,900°/sec	1,900°/sec
Repeatability ^{*2}	X- and Y-Axis	±0.01mm	±0.01mm	±0.015mm	±0.015mm
	Z-Axis	±0.01mm	±0.01mm	±0.01mm	±0.01mm
	R-Axis	±0.01°	±0.01°	±0.01°	±0.01°
Standard Cycle Time ^{*3}	When carrying 1kg of workplace	0.39sec	0.38sec	0.39sec	0.41sec
Machine Weight		27kg	27kg	28kg	29kg
Control Box Weight		20kg			
Drive Method		AC servomotor			
Control Method		PTP (Point to Point) control, CP (Continuous Path) control			
Interpolating Function		3-Dimensional Line and Arc Interpolation			
Position Detection		Absolute Encoder			
Teaching Method		Remote Teaching (JOG) / Manual Data Input (MDI) / Direct Teaching			
Teaching System		JANOME's original software JR C-Points: Simple and broad-use teaching system			
		<ul style="list-style-type: none"> ● Simple: Easy teaching just by registering positions and parameters Optional system programs are available for basic operations and various applications.* ● Broad-use: User-oriented programming including I/O control using point job commands 			
Teaching Pattern		<ul style="list-style-type: none"> ● Programming by teaching pendant (optional) ● Off line teaching using optional JR C-Points (PC software) via PC ● On line teaching using optional JR C-Points (PC software) via PC 			
Programming Capacity		255 programs			
Data Memory Capacity ^{*4}		Maximum 30,000 points			
Simple Sequencer		Maximum 1,000 steps			
External Serial Interface		RS422 1ch (for teaching pendant)			
		RS232C 1ch (for PC: COM1)			
		RS232C 2ch (for external devices: COM2, COM3)			
External Input/Output ^{*5}		I/O-SYS Input: 15 / Output: 14			
		I/O-1 Input: 18 / Output: 22 (4-relay contact)			
		I/O-H Input: 4 / Output: 4 (2-relay contact)			
Tool Wiring and Piping		14 wires for signals, 4 air pipes: Φ4			
Power Supply		AC180~250V (single phase)			
Power Capacity		950VA		1,050VA	
Working Ambience	Ambient Temperature	0~40°C			
	Relative Humidity	20~90% (non-condensing)			

*1: Measured on a machine with regenerative resistors. Maximum speed cannot be achieved under the maximum portable weight setting.

*2: Repeatability was measured at a constant temperature, so absolute precision is not guaranteed.

*3: Measured on a machine with regenerative resistors. Continuous operation cannot be achieved at the maximum cycle time.

*4: The point data capacity will be reduced if the additional function data setting / point job data / sequencer data increases, due to the shared data storage area.

*5: NPN / PNP can be chosen before shipment.

● The specifications may be modified without prior notice to improve quality.

JSTH series

● JS 350TH



● JS 450TH



● JS 550TH



● JS 650TH



● JS 750TH



● JS 880TH



● JS 1000TH



JSTH series Specifications

Model		JS350TH	JS450TH	JS550TH	JS650TH	JS750TH	JS880TH	JS1000TH	
Item									
Axis Type		4 (synchronous control)							
Arm Length	J1 Arm	125mm	225mm	325mm	300mm	400mm	400mm	520mm	
	J2 Arm	225mm	225mm	225mm	350mm	350mm	480mm	480mm	
	J1+J2	350mm	450mm	550mm	650mm	750mm	880mm	1000mm	
Operation Range	J1 Arm	±130°	±130°	±130°	±130°	±130°	±130°	±130°	
	J2 Arm	±150°	±150°	±150°	±150°	±150°	±160°	±160°	
	Z-Axis	200mm	200mm	200mm	200mm	200mm	200mm	200mm	
	R-Axis	±360°	±360°	±360°	±360°	±360°	±360°	±360°	
Maximum Portable Weight	6kg	6kg	6kg	20kg	20kg	20kg	20kg	20kg	
Acceptable Moment of Inertia	0.1kg·m ²	0.1kg·m ²	0.1kg·m ²	0.2kg·m ²	0.2kg·m ²	0.2kg·m ²	0.2kg·m ²	0.2kg·m ²	
Maximum Speed ¹	J1 and J2 (combined)	6,300mm/sec	5,600mm/sec	6,200mm/sec	6,700mm/sec	7,200mm/sec	6,500mm/sec	7,000mm/sec	
	Z-Axis	1,800mm/sec	1,800mm/sec	1,800mm/sec	2,000mm/sec	2,000mm/sec	2,000mm/sec	2,000mm/sec	
	R-Axis	1,900°/sec	1,900°/sec	1,900°/sec	1,800°/sec	1,800°/sec	1,800°/sec	1,800°/sec	
Repeatability ²	X- and Y-Axis	±0.01mm	±0.015mm	±0.015mm	±0.02mm	±0.02mm	±0.025mm	±0.025mm	
	Z-Axis	±0.01mm	±0.01mm	±0.01mm	±0.01mm	±0.01mm	±0.01mm	±0.01mm	
	R-Axis	±0.01°	±0.01°	±0.01°	±0.01°	±0.01°	±0.01°	±0.01°	
Standard Cycle Time ³	When carrying 1kg of workpiece	-	-	-	-	-	-	-	
	When carrying 2kg of workpiece	0.43sec	0.45sec	0.43sec	0.44sec	0.46sec	0.47sec	0.50sec	
Machine Weight		30kg	31kg	32kg	65kg	67kg	68kg	70kg	
Control Box Weight			20kg			27kg			
Drive Method		AC servomotor							
Control Method		PTP (Point to Point) control, CP (Continuous Path) control							
Interpolating Function		3-Dimensional Line and Arc Interpolation							
Position Detection		Absolute Encoder							
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Data Memory Capacity ⁴		Maximum 30,000 points							
Simple Sequencer		Maximum 1,000 steps							
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		RS232C 1ch (for PC: COM1)							
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External Input/Output ⁵		I/O-SYS Input:15/Output:14							
		I/O-1 Input:18/Output:22 (4-relay contact)							
		I/O-H Input:4/Output:4 (2-relay contact)							
Tool Wiring and Piping		14 wires for signals, 4 air pipes: Φ4				14 wires for signals, 4 air pipes: Φ6			
Power Supply		AC180~250V (single phase)							
Power Capacity		1,050VA				1,900VA			
Working Ambience	Ambient Temperature	0~40°C							
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Clean Room Type Models

JS250CL / JS350CL / JS450CL

■ Clean Class 10 (0.3 μ m) *Specifications

- ① The special airtight structure and the vacuuming system minimize dust inside the robot.
- ② Special external conductive coating prevents static electricity.
- ③ Low dust grease is used for the Z-axis spline and ball screw; also, the Z axis is covered by a special antistatic accordion hose.
- ④ The robot's body (without the control box) can be used in both the clean room and regular environments.

■ What's Clean Class 10?

Clean Class 10 is defined by Federal Standard 209D as a particulate count that shall not exceed a total of 10 particles of a size of 0.5 μ m or greater per cubic foot of air.

Cleanliness	Class 10 (Federal Standard 209D)
Ventilator Diameter	Internal Diameter of Vent Pipe: Φ 19
Outlet flow	180NL/min (11Nm ³ /h)

※Common to the robot body and control box



● JS350CL

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2007.01 (S) 1,000